# HyperBO+: Pre-training a universal hierarchical Gaussian process prior for Bayesian optimization

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## Introduction

- BayesOpt requires expert knowledge to select priors.
- Popular solutions: learn the prior from multi-task data, e.g. multi-task BO (Swersky et al., 2013), few-shot BO (Wistuba and Grabocka, 2021) and HyperBO (Wang et al., 2022).
  - Limitations: input domains must be the same for all tasks.
- We present HyperBO+: a pre-training approach for hierarchical Gaussian processes that enables the same prior to work universally for Bayesian optimization on functions with different domains.
- Our contributions:
  - two-step pre-training method that learns a universal hierarchical GP prior.
  - transfer learning BO framework that generalizes to unseen search spaces.
  - analyses on **empirical and theoretical advantages**.

### **Two-step pre-training**

• Estimating GP parameters of each search space. For each function collection  $F_i$  with domain  $\mathcal{X}_i$ , we can infer its GP parameters  $\theta_i$  and noise standard deviation  $\sigma_i$  by minimizing the negative log-likelihood of the dataset as in the original HyperBO:

$$(\widehat{\theta}_{i}, \widehat{\sigma}_{i})_{ML} = \operatorname{argmin}_{\theta, \sigma} - \sum_{j=1}^{M_{i}} \log p(D_{ij} \mid \theta, \sigma).$$

• Estimate the universal prior. Using the estimated  $\{(\hat{\theta}_i, \hat{\sigma}_i)\}_{i=1}^N$  from all datasets, we can use the the maximum likelihood estimator for the universal prior parameter a as  $\hat{a} = \operatorname{argmax}_a p(\{(\hat{\theta}_i, \hat{\sigma}_i)\}_{i=1}^N; a\})$ .

# Generalization: Bayesian optimization on an unseen function with new search spaces

HyperBO+ models functions via a hierarchical GP with pre-trained universal prior parameter a.

• At step t of Bayesian optimization, select x to optimize acquisition function:

### **Problem Formulation**

**Goal:** to optimize unseen black-box functions by pre-training on existing data from functions in **multiple search spaces**, which can have **different numbers of dimensions** for their respective domains.

- Definitions:
  - super-dataset D: all datapoints collected across multiple search spaces.  $D = \{D_i\}_{i=1}^N$ .
  - **dataset**  $D_i$ : the data from a single search space, consists of observations on a collection of black-box functions  $F_i = \{f_{ij}: \mathcal{X}_i \to \mathbb{R}\}_{j=1}^{M_i}$  where functions in  $F_i$  share the same compact search space  $\mathcal{X}_i \in \mathbb{R}^{d_i}$ .  $D_i = \{D_{ij}\}_{j=1}^{M_i}$ .
  - **sub-dataset**  $D_{ij}$ : the collection of datapoints from a single function within a search space.  $D_{ij} = \{(x_k^{ij}, y_k^{ij})\}_{k=1}^{L_{ij}}$ .  $L_{ij}$  is the number of observations on function  $f_{ij}$ .
  - **observation**  $(x_k^{ij}, y_k^{ij})$ : function value perturbed by *i.i.d.* additive Gaussian noise, i.e.  $y_k^{ij} \sim \mathcal{N}(f_{ij}(x_k^{ij}), \sigma_i^2)$ .



$$ac_t(x;\hat{a}) = \sum_{r=1}^{R} \left[ ac_t(x;\theta_r,\sigma_r) p((x_k,y_k)_{k=1}^t | \theta_r,\sigma_r) \right]$$

•  $(\theta_1, \sigma_1), \dots, (\theta_R, \sigma_R)$  are *i.i.d.* samples from the prior distribution  $p((\theta, \sigma); \hat{a})$ .

## Experiments

We demonstrate the strong performance of HyperBO+ compared to baseline methods on two datasets: a **Synthetic Super-dataset** and **HPO-B Superdataset** (Pineda-Arango et al., 2021), a collection of real-world hyperparameter tuning tasks that involves multiple search spaces. Two experiment setups:

- Setup A is designed to demonstrate the ability of HyperBO+ to generalize its learned prior to unseen search spaces. We split the super-dataset into training datasets and testing datasets.
- Setup B aims to to test the ability of HyperBO+ to generalize to new functions in seen search spaces and compare its performance with HyperBO. We split each dataset in the super-dataset into training sub-datasets and testing sub-datasets.

**Baselines**: (1) A hand-specified (and potentially misspecified) hierarchical GP prior, fixed over all search spaces. (2) Random sampling for optimization. (3) HyperBO, only applicable to Setup B. (4) The ground-truth hierarchical GP prior, only available for Synthetic Super-dataset.



- For each i = 1, ..., N, we assume all functions in  $F_i$  are *i.i.d.* function samples from the same GP:  $GP_i = GP(\mu_i, k_i)$ . For each function set  $F_i$  and its corresponding  $GP_i$  with mean function  $\mu_i: \mathcal{X}_i \to \mathbb{R}$  and kernel  $k_i: \mathcal{X}_i \times \mathcal{X}_i \to \mathbb{R}$ , we denote the parameters of  $\mu_i, k_i$  by  $\theta_i$ .
- **Our major assumption**: The GP parameters and noise standard deviation  $\{(\theta_i, \sigma_i)\}_{i=1}^N$  are *i.i.d.* samples from a distribution, as in  $(\theta_i, \sigma_i) \sim p((\theta, \sigma); a)$ . The distribution  $p((\theta, \sigma); a)$  is a *universal prior* for all search spaces.

### Methodology

The HyperBO+ framework consists of mainly two phases: (1) **Training**: estimate the universal prior *a* from the super-dataset  $D = \{D_i\}_{i=1}^N$  with a two-step approach. (2) **Optimization**: running BO with the hierarchical GP parameterized by the learned *a* on testing functions.

### References

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